TABLE 1: PHYSICAL CONSTANTS

NAME	SYMBOL	VALUE
Acceleration due to gravity	g	$9{,}8\ m{\cdot}s^{-2}$
Permittivity of free space	ε_0	$8{,}85 \times 10^{-12}\ Fm^{-1}$

TABLE 2: FORMULAE

FORCE

$F_{net} = ma$	$p = mv$
$f_s^{max} = \mu_s N$	$f_k = \mu_k N$
$F_{net}\Delta t = \Delta p$ $\Delta p = mv_f - mv_i$	$F_g = mg$

WORK, ENERGY AND POWER

$W = F\Delta x\cos\theta$	$U = mgh$ or $Ep = mgh$
$K = \frac{1}{2}mv^2$ or $E_k = \frac{1}{2}mv^2$	$\Delta K = K_f - K_i$ or $\Delta E_k = K_{kf} - K_{ki}$
$M_E = E_k + E_p$	$P = \frac{W}{\Delta t}$
$P_{ave} = Fv_{ave}$	

ELASTICITY, VISCOSITY AND HYDRAULICS

$\sigma = \frac{F}{A}$	$\varepsilon = \frac{\Delta\ell}{L}$
$\frac{\sigma}{\varepsilon} = K$	$\frac{F_1}{A_1} = \frac{F_2}{A_2}$

ELECTROSTATICS

$C = \frac{\kappa \varepsilon_\circ A}{d}$ and $C = \frac{\varepsilon_\circ A}{d}$	$E = \frac{V}{d}$
$C = \frac{Q}{V}$	

CURRENT ELECTRICITY

$R = \frac{V}{I}$	$q = I \Delta t$
$W = VQ$ $W = VI \Delta t$ $W = I^2 R \Delta t$ $W = \frac{V^2 \Delta t}{R}$	$P = \frac{W}{\Delta t}$ $P = VI$ $P = I^2 R$ $P = \frac{V^2}{R}$
$R_s = R_1 + R_2 + \ldots$	$\frac{1}{R_p} = \frac{1}{R_1} + \frac{1}{R_2} + \ldots$

ELECTROMAGNETISM

$\phi = BA$	$\varepsilon = -N\frac{\Delta\phi}{\Delta t}$
$\frac{V_s}{V_p} = \frac{N_s}{N_p}$	